Several Uses for EISCAT3D

<u>Juha Vierinen</u>¹, Markku Lehtinen¹, Jussi Markkanen², Ilkka Virtanen³, Holger Krag⁴ and Pravas Mahapatra¹

> ¹Sodankylä Geophysical Observatory ²EISCAT Scientific Association ³ University of Oulu ⁴ ESA

> > June 8, 2009

Sac

Overview

- Meteor ideas (synthesized beams for statistical studies, simulated "mono-pulse feed" for interferometric angular measurement)
- Space Debris (statistical measurement, passive and active orbital elements determination)

< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > <

- Planetary radar
- Multi-purpose experiments
- Implications for E3D design, some ideas

Meteors

- Multi-static meteor head echo observations can be used to determine trajectory and correct radar cross-section (a lot of publications by the Swedish group)
- Trajectory could also be estimated using interferometric directional information using several overlapping beams
- Synthesized beams can be used to generate wide and narrow beams (e.g. Chau 2009)
- Both circular polarizations would give more information of the target (e.g. Close 2008)

 A long term data-set would give a better estimate of the global meteoroidal mass flux

Meteors



J.L. Chau et al. / Journal of Atmospheric and Solar-Terrestrial Physics 71 (2009) 636-643

Space Debris

- There is considerable interest for surveying the space environment (EU SSA program). This includes space debris, space weather and near earth objects.
- E3D can contribute to all of these
- Passive (using target angular velocities) and active (tracking) orbital element determination for space debris
- Current models predict that space debris is already in a collisional chain reaction that will eventually make near earth orbits unusable (several papers in the ESA Space Debris Conference 2009 proceedings)



News Front Page

Americas

Europe

ЦΚ

Asia-Pacific

Middle East

South Asia

Business

Science &

Technology

Environment

Entertainment

Video and Audio

Have Your Say

Country Profiles

Special Reports

Related BBC sites

In Pictures

Snort

Weather

On This Day

Editors' Blog

Site Version

O UK Version

BBC World Service

Also in the news

Health



E-mail this to a friend

Printable version

Russian and US satellites collide

US and Russian communications satellites have collided in space in what is thought to be the biggest incident of its kind to date.

The US commercial Iridium spacecraft hit a defunct Russian satellite at an altitude of about 800km (500 miles) over Siberia on Tuesday, Nasa said.

The risk to the International

Space Station and a shuttle launch planned for later this month is said to be low

The impact produced a cloud of debris, which will be tracked into the future.

Since the Soviets launched Sputnik in 1957, it is estimated about 6,000 satellites have been put in orbit.

Satellite operators are all too aware that the chances of a collision are increasing.

66

necessary

John Yembrick

Nasa spokesman

The Americans are now following the debris path from the impact. It is hoped that most of it will fall to Earth and burn up in the atmosphere.

Shuttle launch

The concern is whether the debris

will spread and pose any risk to the ISS, which is orbiting the Earth International Version some 435km below the course of the collision. About the versions



Iridium spacecraft provide satellite phone services.

Satellite begins climate mission

The space station does

have the capability of doing a

debris-avoidance manoeuvre if

23 Jan 09 | Science & Environment Nigerian satellite fails in space.

SEE ALSO

13 Nov 08 | Africa

03 Feb 09 | Middle East

OBA: Space debris 07 Oct 07 | Science & Environment

Sat collision highlights growing threat

12 Feb 09 | Science & Environment

Iran launches homegrown satellite

03 Feb 09 | Science & Environment

Plans for UK satellite launcher

RELATED BBC LINKS

Space junk

RELATED INTERNET LINKS

Nasa

99

- ISS
- Tridium
- US space surveillance

The BBC is not responsible for the content of external internet sites

TOP SCIENCE & ENVIRONMENT STORIES

- Nasa's Discovery returns to Earth
- Wind nowered car breaks record
- Cities switch off for Earth Houre 😑 🕟 🧃 📄

EISCAT Satellite Collision Survey



PROOF simulation (Range vs. Time)

◆□▶ ◆□▶ ◆三▶ ◆三▶ 三三 のへぐ

EISCAT tracking test



<ロト <回ト < 注ト < 注ト

æ

Envisat crossings

Event 50



Range (km)

Planetary Radar

- The current array design cannot point low enough to allow Lunar or planetary observations
- One idea: use dipole elements and slope array by, say 12°. This would also increase gain at field-aligned direction
- If all directions are needed, a mound shaped positioning is possible





Lunar Radar

► The VHF transmission frequency of ≈ 200 MHz means deeper penetration in the regolith (15-150 m, Campbell 2006).

< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > <

- Lower frequency, clock is less important than with the UHF system
- Both circular / linear receive polarizations are needed
- Phased array allows interferometric observations (e.g. Thompson 1978)

Moon elevation 2009-2010



Moon passes

Ideally, the E3D system should give as much bang per euro as possible, by simultaneously measuring:

- All regions of the ionosphere
- Meteor head echos (event rate pprox 1000/h)
- Space debris (event rate \approx 40/h)

Space Debris



◆□▶ ◆□▶ ◆臣▶ ◆臣▶ 三臣 - のへで

Meteor head echos



Time of day histogram



Velocity histogram



2 8 100 150 200 Range (km)



Frequency

Velocity vs. range

Range (km)



00 01 01 -600000 -200000 600000 LCOS Velocity (mit)

Velocity vs. MF



Range vs. MF



Range (km)

Plasma parameters



Sac



◆□▶ ◆□▶ ◆臣▶ ◆臣▶ 臣 のへぐ

Uniform IPP missing ranges



Figure 6: Event rate v altitude.

At

э

・ロト ・聞ト ・ヨト ・ヨト

EISCAT 30-50% ranges blocked by transmission and ground clutter.

Aperiodic IPP experiment



Multi-pulse codes [Farley, 1972], Simple Difference covers [Clinger and Ness, 1976], ATC [Uppala and Sahr, 1996, 1994], Jicamarca [Chau et al., 2004], SMPRF [Pirttilä and Lehtinen, 1999], PPATC [Virtanen et al., 2008, 2009]

Ramped IPP timing

Ramped Spacing



Duty-cycle locally variable

$$IPP = \{a, a + k, a + 2k, \cdots, a + (N-1)k\}$$

Ramped IPP timing



・ロト ・四ト ・ヨト ・ヨト

æ

Ramped IPP

TX and ground clutter is black

Arithmetic Modulus Timing



Arithmetic Modulus Spacing

- [Uppala and Sahr, 1996]
- Duty-cycle less variable locally
- More evenly spaced

 $IPP = \{a, a+(k \mod p), a+(2k \mod p), \cdots, a+((N-1)k \mod p)\}$

Arithmetic Modulus Progression



TX and ground clutter is black

Radar efficiency comparison



- Ramped IPP has less oscillation of efficiency
- Arithmetic Modulus coding has bands of 100% efficiency

イロト イポト イヨト イヨト

э

The Spade09 Experiment: Coding



- Ramped IPP
- Coding optimized for ionospheric work
- ▶ Random code group, 159 codes, 53 IPPs
- ▶ 15 μ s baud length
- 22 bauds

Why random coding?

Measurement equation:

$$m = Ax + \xi \tag{1}$$

Maximum likelihood solution:

$$x_{ML} = (A^H A)^{-1} A^H m \tag{2}$$

- A random transmission code is rarely optimal for a single echo, but under the asumption of target stationarity, it approaches an optimal coding with enough repetitions. A^HA ≈ I (Sulzer 1986)
- In the case of incoherent scatter, our random code is 0.01% less than optimal in terms of estimation variance.

Implications for E3D

- Planetary radar is not possible without south facing low elevation pointings (preferably down to 65° zenith angle)
- Several simultaneous beams should be possible, in order to determine angular position of space debris, meteors, and to enable interferometric Lunar observations
- Proper ionospheric plasma parameter estimation requires detection of space debris and meteors, so that they can be removed in amplitude domain, a general operating mode of the system should optimally be able to estimate all of these.

Implications for E3D

- Planetary radar is not possible without south facing low elevation pointings (preferably down to 65° zenith angle)
- Several simultaneous beams should be possible, in order to determine angular position of space debris, meteors, and to enable interferometric Lunar observations
- Proper ionospheric plasma parameter estimation requires detection of space debris and meteors, so that they can be removed in amplitude domain, a general operating mode of the system should optimally be able to estimate all of these.

Implications for E3D

- Planetary radar is not possible without south facing low elevation pointings (preferably down to 65° zenith angle)
- Several simultaneous beams should be possible, in order to determine angular position of space debris, meteors, and to enable interferometric Lunar observations
- Proper ionospheric plasma parameter estimation requires detection of space debris and meteors, so that they can be removed in amplitude domain, a general operating mode of the system should optimally be able to estimate all of these.

Raw Voltage Data Compression

57 % Compressed radar signal



Real part



▲口 → ▲圖 → ▲ 臣 → ▲ 臣 → □ 臣 □

Raw Voltage Data Compression



◆□> ◆□> ◆三> ◆三> ・三 ・ のへの

- J. L. Chau, D. L. Hysell, P. M. Reyes, and M. A. Milla. Improved spectral observations of equatorial spread F echoes at jicamarca using aperiodic transmitter coding. *Journal of Atmospheric and Solar-Terrestrial Physics*, 66:1543–1548, 2004. doi: 10.1016/j.jastp.2004.07.002.
- W. Clinger and J. W. Van Ness. On unequally spaced time points in time series. *The Annals of Statistics*, 4:736–745, 1976.
- D. T. Farley. Multiple-pulse incoherent-scatter correlation function measurements. *Radio Science*, pages 661+, 1972.
- J. Pirttilä and M. Lehtinen. Solving the range-doppler dilemma with ambiguity-free measurements developed for incoherent scatter radars. *COST 75, Advanced Weather radar systems, International seminar*, pages 557–568, 1999.
- S. V. Uppala and J. D. Sahr. Spectrum estimation of moderately overspread radar targets using aperiodic transmitter coding. *Radio Science*, 29:611623, 1994.
- S. V. Uppala and J. D. Sahr. Aperiodic transmitter waveforms for spectrum estimation of moderately overspread targets: new codes and a design rule. *IEEE Transactions on Geoscience and Remote Sensing* 34:12851287, 1996, doi: 10.1007/10.1007/10.1007